

CPH 931 — Fall 2009 — Dr. Charnigo

Lecture 4

Nonlinear mean response and nonparametric regression

Flexibility in modeling the mean response. Suppose that we have a single continuous explanatory variable X . The linear regression model says that

$$m(x) = \alpha + \beta x \quad (1)$$

and

$$Y_i = m(x_i) + \epsilon_i. \quad (2)$$

In practice the mean response is almost never exactly linear in x . We usually live with the linear specification in (1) because we believe that it is not a serious departure from the truth.

From your calculus course you may recall Taylor's Theorem, which says that any smooth function is well approximated by a straight line if you confine attention to a small enough interval. This idea is illustrated in the figure on the next page.

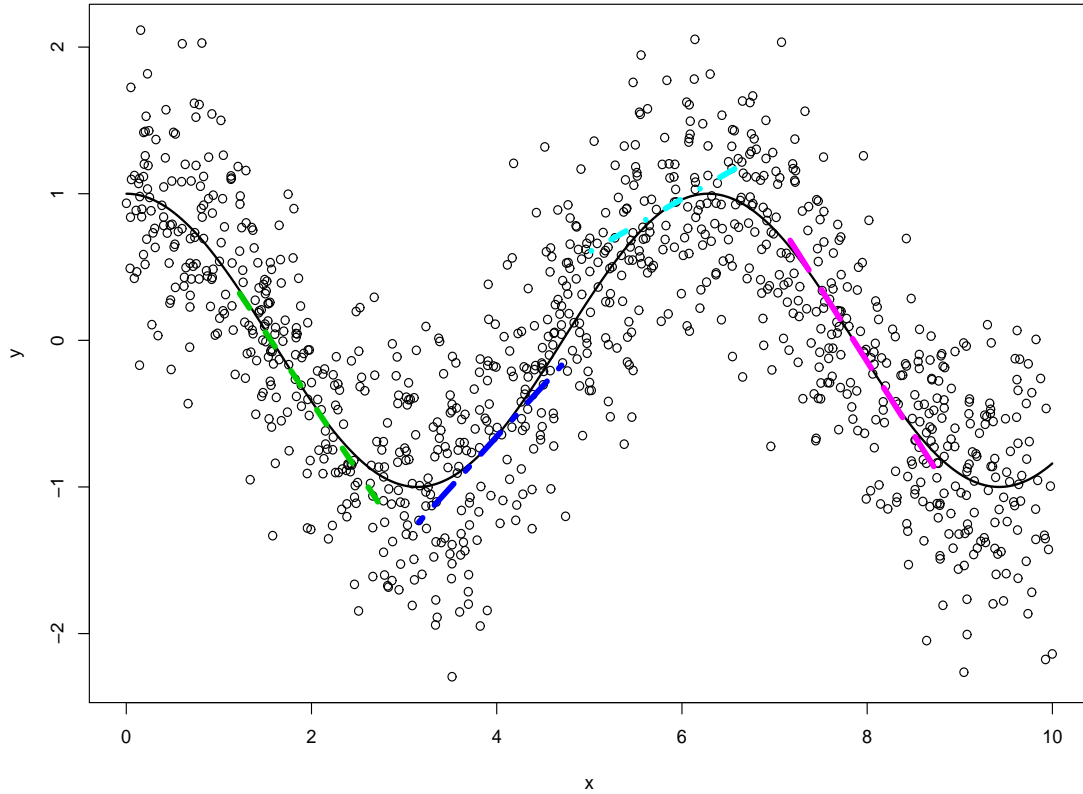
The linear specification is convenient for testing the straw-man null hypothesis of no association between X and Y (all we have to do is see whether $\hat{\beta}$ differs significantly from zero) and is highly amenable to interpretation (increasing X by one unit increases the expected value of Y by β units).

However, there may be some occasions on which we desire more flexibility in modeling the mean response.

Example. The data set {BWeight.xls} provides birthweights (grams) and gestational ages (weeks) for 700 infants. I used ordinary least squares to estimate the expected value of birthweight as a linear function of gestational age.

The results of the ordinary least squares analysis are summarized on page

Illustration of Taylor's Theorem



1 of {infresults.rtf}. The slope coefficient estimate of 125.2 tells us that, for every one-week increase in gestational age, the expected birthweight is estimated to increase by 125.2 grams. Is this reasonable?

Page 2 of {infresults.rtf} shows a scatterplot of birthweights against gestational ages with the fitted regression line superimposed. The fitted regression line appears too high both for unusually low and for unusually high gestational ages. However, this is not a failure of ordinary least squares *per se*. There is no way to draw a straight line through these points without being way off for some gestational ages; whatever approach that we might employ to estimate α and β would fail. The real problem is the linear specification.

Nonparametric regression and LOESS smoothing. There exist several nonparametric regression methods. They are so called because they do not require us to express the mean response in terms of finitely many parameters like α and β . The specific method that we will consider today is called LOESS smoothing and is available in SAS through the LOESS procedure.

The basic idea is as follows. Let x_0 denote a specific value of X . For x near x_0 , we have the approximate linear relationship

$$m(x) \approx \alpha_{x_0} + \beta_{x_0}x. \quad (3)$$

The x_0 subscripts on α_{x_0} and β_{x_0} remind us that the approximating linear relationship should depend on x_0 . The figure on the preceding page illustrates: for x near $x_0 = 2$ we have (green line) $m(x) \approx 1.40 - 0.91x$, for x near $x_0 = 4$ we have (blue line) $m(x) \approx -3.68 + 0.76x$, for x near $x_0 = 6$ we have (turquoise line) $m(x) \approx -0.76 + 0.28x$, and for x near $x_0 = 8$ we have (purple line) $m(x) \approx 7.77 - 0.99x$.

So, given a specific value x_0 , how can we estimate α_{x_0} and β_{x_0} ? The answer is that we will employ weighted least squares; we will estimate α_{x_0} and β_{x_0} by minimizing

$$\sum_{i=1}^n w_{i;x_0} (y_i - r_{0;x_0} - r_{1;x_0}x_i)^2. \quad (4)$$

However, the weights $w_{i;x_0}$ will not be chosen in relation to error variances; although we have discarded assumption (1), we are still assuming (2) with errors that have a common variance. Rather, the weights $w_{i;x_0}$ will be chosen to place more emphasis on the observations with x_i close to x_0 . Thus, observations with x_i close to 2 will do most of the work in estimating the green line on the preceding page, while observations with x_i close to 4 will do most of the work in estimating the blue line.

More specifically, we choose (or rely on SAS to choose for us) a number $q \ll n$ such that nonzero weights are assigned only to the q observations

for which x_i is closest to x_0 ; all other observations receive zero weights. The nonzero weights are assigned as follows. Let $d_1 \leq d_2 \leq \dots \leq d_q$ denote the distances from x_i to x_0 for the q observations. The observation corresponding to the distance d_j receives a weight of $[1 - (d_j/d_q)^3]^3$. Hence, observations corresponding to smaller distances receive greater weights. The estimates of α_{x_0} and β_{x_0} are then determined using these weights.

The estimate of $m(x_0)$ resulting from this procedure is $\hat{\alpha}_{x_0} + \hat{\beta}_{x_0}x_0$, where $\hat{\alpha}_{x_0}$ and $\hat{\beta}_{x_0}$ denote the estimates of α_{x_0} and β_{x_0} . By varying x_0 through the entire range of X and repeating the above computations for each x_0 , we can estimate the mean response over the entire range of X .

Example, continued. Refer to page 5 of {infresults.rtf}. There are many pieces of information here, and we will not be concerned with all of them. However, I will call your attention to a few items. The entry of 175 for “Points in Local Neighborhood” tells us what SAS used for q . The “Smoothing Parameter” equals 0.25071 and is basically q/n , apart from minor discrepancies due to rounding. Hence, in this example only 25% of the observations were used to estimate α_{x_0} and β_{x_0} for each x_0 . The “AICC” is a measure that SAS uses to describe the quality of the fit associated with a given value for the “Smoothing Parameter”; lower is better.

Page 6 of {infresults.rtf} provides a visual display of the results. Although there is some “jiggling” (partly because gestational age is measured only to the nearest week), the smooth curve shown here is a more credible estimate of mean birthweight as a function of gestational age than the straight line shown on page 2 (or any other straight line).

Remark on LOESS smoothing. Although LOESS smoothing can be generalized to accommodate multiple explanatory variables, making sense of the results is difficult when there are more than two explanatory variables. This is because, in the absence of parameters, we must visualize the results to make sense of them; human beings can only see cross sections when there are more than three spatial dimensions.

Discussion questions. If we were uncomfortable assuming that $m(x) = \alpha + \beta x$, what other option besides nonparametric regression might we consider? What would be the advantages and disadvantages of this option?

Handling missing data

Introduction. We have discussed how to handle various problems preventing successful application of ordinary least squares in fitting a linear regression model. Some of our solutions have entailed using an estimation framework other than ordinary least squares (weighted least squares for heteroscedasticity, ridge regression for multicollinearity, robust regression for nonnormal errors or outliers), while some have entailed using a more general statistical model (nonparametric regression model when the mean response is not a linear function, linear mixed model when the errors are correlated due to repeated measurements).

Now we consider another problem, that of missing data. This problem is not one of statistical assumptions being violated. Rather, missing data can arise for one of the following reasons.

1. Some subjects may refuse to provide sensitive information.
2. Some subjects may drop out of a study.

3. A researcher may find a gross error in a database, but correcting the gross error may not be possible because the researcher no longer has contact with the subject. Thus, the gross error is effectively replaced by a missing value.
4. A researcher may not be able to acquire data on all variables for some subjects. This can happen if the researcher is acquiring data from preexisting medical records rather than contemporaneously as part of his/her study.

Types of missing data. Consider a data set with a variable V that has some missing values and variables U_1, \dots, U_k that do not have any missing values.

Data are missing completely at random (MCAR) if the probability of observing V does not depend on the true value of V — assumed to exist whether or not we actually observe it — or on the values of U_1, \dots, U_k :

$$\mathbb{P}(\text{observing } V \mid V = v, U_1 = u_1, \dots, U_k = u_k) = \text{constant}.$$

Data are missing at random (MAR) if the probability of observing V does not depend on the true value of V after we control for U_1, \dots, U_k :

$$\mathbb{P}(\text{observing } V \mid V = v, U_1 = u_1, \dots, U_k = u_k) = f(u_1, \dots, u_k).$$

Data are missing not at random (MNAR) if the probability of observing V depends on the true value of V even after we control for U_1, \dots, U_k :

$$\mathbb{P}(\text{observing } V \mid V = v, U_1 = u_1, \dots, U_k = u_k) = f(v, u_1, \dots, u_k).$$

Illustrating types of missing data. Suppose that we survey patients at a medical practice as part of an investigation on factors relating to patients' exercise habits. Not ruling out that socioeconomic factors may relate to patients' exercise habits, one question we may ask of patients is how much money they make.

However, some patients may regard this as sensitive information. In particular, suppose that 30% of “wealthy” patients decline to respond, 20%

of “middle class” patients decline to respond, and 40% of “poor” patients decline to respond. (Exact definitions for wealthy, middle class, and poor are unimportant here.)

Under these suppositions, the income data are not MCAR: the probability of observing a patient’s income depends on the patient’s true income because this probability is greater for a middle class patient than for a wealthy patient or a poor patient.

However, if there are other items on the survey — such as occupation, educational attainment, and manner of payment for medical services — that are strongly related to income, then the income data may be (approximately) MAR: the probability of observing a patient’s income may be (approximately) expressed as a function of the patient’s occupation, educational attainment, and manner of payment for medical services.

On the other hand, if there are no other items on the survey that are strongly related to income, then the income data are MNAR.

Implications for statistical inference. By now you have encountered many statistical models, but there is almost always a common theme to the statistical inference: we want to quantify population-level relationships between a response variable and one or more explanatory variables.

When the data are MNAR, the relationships between V and U_1, \dots, U_k may differ between the subpopulation for which V is observable and the subpopulation for which V is not observable. Since we can only observe V in members of the first subpopulation, quantifying population-level relationships is problematic. If we naively fit a statistical model using only those records without missing values, then we are quantifying relationships not in the full population but in the subpopulation for which V is observable.

Sophisticated approaches for analyzing MNAR data exist, but they are cumbersome. In particular, they may entail explicit estimation of

$\mathbb{P}(\text{observing } V \mid V = v, U_1 = u_1, \dots, U_k = u_k)$ as a function of v, u_1, \dots, u_k . Thus, we may prefer trying to avoid MNAR data altogether by collecting information on many variables. Even though having MCAR data is often too much to hope for, the data may be (approximately) MAR if we are sufficiently broad in our collection of information.

When the data are MAR, the relationships between V and U_1, \dots, U_k do not differ between the subpopulation for which V is observable and the subpopulation for which V is not observable. Moreover, quantifying population-level relationships is possible without explicitly estimating $\mathbb{P}(\text{observing } V \mid V = v, U_1 = u_1, \dots, U_k = u_k)$.

For the rest of this lecture, I assume that the data are MAR.

Motivating example. In {Mercury.xls} I have a modified version of the data from {<http://lib.stat.cmu.edu/DASL/Datafiles/MercuryinBass.html>}. The website's description of the original data set is as follows.

“Largemouth bass were studied in 53 different Florida lakes to examine the factors that influence the level of mercury contamination. Water samples were collected from the surface of the middle of each lake in August 1990 and then again in March 1991. The pH level, the amount of chlorophyll, calcium, and alkalinity were measured in each sample. The average of the August and March values were used in the analysis. Next, a sample of fish was taken from each lake with sample sizes ranging from 4 to 44 fish. The age of each fish and mercury concentration in the muscle tissue was measured. (Note: Since fish absorb mercury over time, older fish will tend to have higher concentrations). Thus, to make a fair comparison of the fish in different lakes, the investigators used a regression estimate of the expected mercury concentration in a three year old fish as the standardized value for each lake. Finally, in 10 of the 53 lakes, the age of the individual fish could not be determined and the average mercury concentration of the

sampled fish was used instead of the standardized value.”

The modification I made to {Mercury.xls} was to set the 3-year standard mercury values to missing for the 10 lakes in which the ages of the individual fish could not be determined. Thus, there are missing values on 18.9% of the records, which is greater than the 10% – 15% at which I would begin to feel uncomfortable confining attention to records without missing values.

On page 1 of {Mercury.rtf} are results for a linear regression model fit by ordinary least squares, using only the 43 observations with non-missing 3-year standard mercury values. The response variable is a log-transformed version of 3-year standard mercury, hereafter denoted Y . The sole explanatory variable is the lake’s pH level, hereafter denoted X . Page 2 shows a scatterplot of Y values against X values along with the fitted regression line $\hat{y} = 1.53885 - 0.35773 \cdot x$. Note that $R^2 = 0.3818$.

Single imputation. Suppose that I ask you to guess the value of Y for Lake Annie in our motivating example. One possibility, based on “imputation by mean substitution”, is the sample mean of Y , which is -0.82713 .

However, such a guess ignores the potentially relevant information that the value of X for Lake Annie is 5.1. A better guess, based on “imputation by regression”, is $1.53885 - 0.35773 \cdot 5.1 = -0.28557$.

We can similarly impute a value of Y for each of the other nine lakes in which the ages of the individual fish could not be determined. This is referred to as “single imputation” because we are making a single number best guess for the value of Y wherever it is missing.

Note that, in this example, the variable on which missing values occur is the response variable (i.e., $V = Y$, $k = 1$, and $U_1 = X$). If missing values had occurred on the explanatory variable, then to perform single imputation we could have employed an auxiliary linear regression model in which the roles of X and Y were reversed.

Consequences of single imputation. On page 3 of {Mercury.rtf} are results for a linear regression model fit by ordinary least squares, using all 53 observations and treating the singly imputed values as if they had been observed in the first place. Page 4 provides the corresponding scatterplot.

Discussion questions. What has happened to the estimates of the intercept and slope? What has happened to R^2 ? If published, why would the results on page 3 be misleading?

Another difficulty with single imputation. Aside from the problems identified in the discussion questions, another difficulty with single imputation is that many data sets will have more than one variable with missing values.

Consider a data set with variables V_1 and V_2 that have some missing values — not necessarily on the same subjects — and variables U_1, \dots, U_k that do not have any missing values. (The definitions of MCAR, MAR, and MNAR can be generalized to this situation. We continue to assume that the data are MAR, which is to say that the probabilities of observing V_1 and V_2 do not depend on the true values of V_1 and V_2 after we control for U_1, \dots, U_k .) What if we wish to impute values for V_1 and V_2 ?

Mean substitution is possible, but this may be undesirable since U_1, \dots, U_k may provide clues on the missing values of V_1 and V_2 .

Imputation by regressing V_1 on U_1, \dots, U_k and V_2 on U_1, \dots, U_k is possible, but what if V_1 and V_2 are correlated? Then not using V_2 to impute values for V_1 is failing to use clues provided by V_2 on the missing values of V_1 (and vice versa). On the other hand, we cannot use V_2 to impute values for V_1 on subjects for whom the values of V_2 are also missing. Consequently, imputation by regression seems piecemeal and haphazard.

Expectation maximization. The difficulty noted above can be overcome by using an “expectation maximization” (EM) algorithm to estimate the means, variances, and covariances of $V_1, V_2, U_1, \dots, U_k$. Once these means, variances, and covariances are estimated, we can make our best guesses for the missing values using all available clues in each instance.

A technical assumption for the EM algorithm is that $V_1, V_2, U_1, \dots, U_k$ have a multivariate normal distribution. Since that is only possible if $V_1, V_2, U_1, \dots, U_k$ are individually normally distributed, technically the EM algorithm is not valid if one or more of the variables in the data set is dichotomous. Still, people often use the EM algorithm even if some of the variables in the data set are dichotomous. However, if V_1 (or V_2) is dichotomous and coded as (say) 0 or 1, then the best guesses for the missing values of V_1 (or V_2) must be rounded.

Multiple imputation. Returning to page 4 of {Mercury.rtf}, the situation would seem less unsatisfactory if the imputed values did not all fall on the fitted regression line. Indeed, let us imagine randomly perturbing the imputed values, moving some above the fitted regression line and some below.

In general, rather than working with best guesses for the missing values of V (or of V_1 and V_2), we can work with random perturbations of best guesses. Then we are not artificially diminishing the uncertainty associated with not observing V . A method called “Markov Chain Monte Carlo” (MCMC) uses the output from the EM algorithm to generate random perturbations of best guesses. Again, if V is dichotomous, then the random perturbations of best guesses must be rounded.

Page 5 of {Mercury.rtf} shows (“EM (Posterior Mode) Estimates”) the estimated means, variances, and covariance for Y and X based on the EM

algorithm.

Pages 7 through 14 show five “complete” data sets generated via MCMC. Values of Y that were not missing have not been altered. Values of Y that were missing have been filled in with random perturbations of best guesses. In the first complete data set, the filled-in value of Y for Lake Annie (record 2) is 0.23114. In the second complete data set, the filled-in value of Y for Lake Annie (record 55) is -0.23191. The corresponding filled-in values from the other three complete data sets are -0.28748, -0.61005, and 0.66434.

The process of creating multiple complete data sets in this manner is called multiple imputation.

Combining results from complete data sets. Once we have performed multiple imputation, we can fit our statistical model using each of the complete data sets. Pages 15 through 19 of {Mercury.rtf} show the results from the five complete data sets for fitting a linear regression model with Y as the response variable and X as the sole explanatory variable. Each set of parameter estimates is slightly different, since the random perturbations used to create each complete data set were different.

Of course, we do not want to report five different estimates for the intercept and five different estimates for the slope. We need to somehow combine the five sets of parameter estimates into “overall” estimates for the intercept and slope. The intuitive choice — to simply average over the complete data sets — is in fact correct. So, we average 1.31402, 1.86004, 2.23131, 1.61610, 1.50964 to get 1.706221. And, we average -0.32436, -0.40643, -0.46546, -0.37073, -0.35121 to get -0.383640.

The overall estimates 1.706221 and -0.383640 are shown on page 20 of {Mercury.rtf}, along with standard errors calculated by

$$\sqrt{W + (m + 1)B/m},$$

where

$$W := \sum_{j=1}^m \left\{ se(\hat{\theta}_j) \right\}^2 / m,$$

$$B := \sum_{j=1}^m \left(\hat{\theta}_j - \sum_{k=1}^m \hat{\theta}_k / m \right)^2 / (m - 1),$$

$\hat{\theta}_j$ is the estimate of θ (generic notation for a parameter such as an intercept or slope) based on the j^{th} complete data set, $se(\hat{\theta}_j)$ is the corresponding standard error, and m is the number of complete data sets. Confidence intervals and p-values are also reported, using a T reference distribution on degrees of freedom calculated by

$$(m - 1) \left(1 + \frac{1}{(1 + 1/m)(B/W)} \right)^2.$$

Closing remarks on multiple imputation. A few remarks are in order.

1. Although the choice to create $m = 5$ complete data sets may seem arbitrary, this is accepted practice.
2. Page 20 of {Mercury.rtf} shows that we did not gain much from multiple imputation in this example. The coefficient estimates and standard errors are not much different from what they were in the original analysis based on records without missing values. Thus, the original analysis appears to have been adequate in this example — at least to the extent that the expected value of log 3-year standard mercury is believed to be linear in the lake's pH level.
3. Multiple imputation can also be used when there are missing values on one or more explanatory variables and when there are missing values on both the response variable and one or more explanatory variables.

My past experiences suggest that multiple imputation is more likely to be helpful in these situations than when the missing values occur solely on the response variable.

4. While today's lecture sought to provide a tool for handling missing data in a linear regression setting, multiple imputation can also be used with other (parametric) statistical models, such as logistic regression and linear mixed models.